

**FIRST SEMESTER 2022-2023**

# Course Handout Part II

Date: August 29th, 2022

In addition to part‑I (General Handout for all courses appended to the time table) this portion gives further specific details regarding the course.

**Course No.** : **MATH F212**

**Course Name** : **Optimization**

**Instructor‑in‑charge :** P.T.V. Praveen Kumar

**Instructor**  P.T.V. Praveen Kumar , D. K. Satpathi, K. Venkataratnam, Sumit Kumar Vishwakarma

1. **Scope and Objective of the Course:**

Engineers, scientists, analysts, and managers are often faced with the challenge of making trade-offs between different factors in order to achieve desirable outcomes. Optimization is the process of choosing these trade-offs in the best way. Optimization problems, having reached a degree of maturity over the past several years, are encountered in physical sciences, engineering, economics, industry, planning, and many other areas of human activity. The objective of the course is set to familiarize students with standard methods of solving optimization problems.

This course deals with details of various aspects associated with Optimization. These include a description of optimization techniques, namely, Linear Programming and Nonlinear Programming, and their applications to various engineering and science disciplines, including economics and finance. Multi-objective Optimization, which handles optimization aspects of more than one objective, is also discussed. A brief and informative description of Nontraditional optimization techniques such as Genetic Algorithms is also provided.

**2. Text Book:**

**T1 HA Taha, *Operations Research: An Introduction*, Pearson Education, 10/E, 2019.**

**Reference Books:**

R1 SS Rao, *Engineering Optimization: Theory and Practice*, New Age International (P) Limited, Third Edition, 1996

R2 FS Hillier and GJ Lieberman, *Introduction to Operations Research*, TMH, 11/E, 2021.

R3 WL Winston, *Operations Research: Applications and Algorithms*, Thomson Learning, 4th Edition, 2004

R4 Kalyanmoy Deb, Optimization for Engineering Design:Algorithms and Examples,PHI, 2/E,2012.

**3. Course Plan:**

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| --- | --- | --- | --- |
| **Lecture Nos.** | **Learning Objectives** | **Topics to be Covered** | **Chapter in the Text Book** |
| 1 | Understand the concepts of Optimization. Learn basic optimization techniques | Introduction to Optimization |  |
| 2-4 | Understand and develop Linear Programming models for mathematical problems | Two variable LP model, Graphical LP solution, Selected LP applications, Convex Set | T1 (2.1, 2,2, 2.4, 7.1) |
| 5-6  7-9  10-12 | Understand different techniques available for solving two, multivariate LP problems. | LP model in equation form, Transition from graphical to algebraic solution  The Simplex Method Generalized simplex tableau in matrix form, Revised Simplex Method.  Artificial starting solution  Special cases in the simplex method | T1 (3.1, 7.1.1 , 3.2)    T1(3.3., 7.1.2, 7.2)  T1(3.4, 3.5) |
| 13-14  15-16  17-19 | Understand and solve special cases in the LP problems, introduce sensitivity analysis to re-evaluate a solution. Practical application of LP for solving real time problems | Definition of Dual Problem, Duality, Primal-Dual Relationships.  Economic Interpretation of Duality, Additional simplex algorithms (Dual Simplex Method, Generalized Simplex Algorithm),  Post optimal Analysis | T1 (4.1, 7.4,4.2)    T1(4.3, 4.4)  T1(4.5) |
| 20-22  23 | Understand special cases of simplex problems and its procedures. | Definition of transportation problem, The transportation Algorithm,  The Assignment Model | T1 (5.1, 5.3)  T1(5.4) |
| 24-25 | Understand multiple objective optimization problems and develop models for solving them | Goal Programming Formulation | T1 (8.1, 8.2) |
| 26-28 | Understand Integer Programming Problems and different techniques for solving IPP | Formulation of IP problem  Branch and Bound method for solving IPP  Cutting Plane method | T1 (9.1, 9.2) |
| 29  30-31  32-33  34-35    36-38 | Understand the difference between LPP and Nonlinear Programming Problems. Solve Nonlinear Programming Problems | Unconstrained problems, Convex and concave functions,  Elimination Methods: Fibonacci Method and Golden Section Method,  Gradient of a Function, Descent Methods: Steepest Descent Method and Conjugate Gradient Method,  Karush-Kuhn-Tucker (KKT) Conditions,  Quadratic Programming, | T1 (20.1)  R1 (5.7)    T1 (21.1.1) T1(21.1.2)  R1( 6.11,6.12)    T1 (20.2.2)  T1(21.2.2) |
| 39-40 | Introduce Evolutionary Computation Techniques | Drawbacks of the Classical Techniques, Introduction to Nontraditional Optimization Techniques (Genetic Algorithms, Differential Evolution, etc.) | R4 |

**5. Evaluation Scheme:**

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| --- | --- | --- | --- | --- |
| **Evaluation Component** | **Duration** | **Weightage** | **Date & Time** | **Nature of Component** |
| Quiz 1 | 15 Minutes | 15% |  | CB |
| Mid Semester | 90 Minutes | 30% | 04/11 11.00 - 12.30PM | OB |
| Quiz 2 | 15 Minutes | 15% |  | CB |
| Compre | 180 Minutes | 40% | 27/12 AN | CB |

\* The total marks of all the components taken together will be 200.

**6. Notices:** All notices about the course will be put on CMS.

**7. Consultation Hour:** To be announced in the class by the respective Instructors.

**8. Make-up:** Make up for the tests will normally be held in the following week. Make up will be Granted only in genuine cases. Permission must be taken in advance except in extreme cases.

9. **Academic Honesty and Integrity Policy:** Academic honesty and integrity are to be maintained by all the students throughout the semester and no type of academic dishonesty is acceptable.